



USB DrDAQ[®]

Data Logger

Programmer's Guide



Contents

1	Introduction	1
1	Overview	1
2	License agreement	1
3	Trademarks	2
4	Software updates	2
2	Writing your own software	3
1	About the driver	3
2	Installing the driver	3
3	Connecting the logger	3
4	Capture modes	3
5	USB DrDAQ scaling files (.DDS)	4
3	USB DrDAQ API functions	7
1	UsbDrDaqCloseUnit	9
2	UsbDrDaqEnableRGBLED	10
3	UsbDrDaqGetChannellInfo	11
4	UsbDrDaqGetInput	12
5	UsbDrDaqGetPulseCount	13
6	UsbDrDaqGetScalings	14
7	UsbDrDaqGetSingle	15
8	UsbDrDaqGetSingleF	16
9	UsbDrDaqGetTriggerTimeOffsetNs	17
10	UsbDrDaqGetUnitInfo	18
11	UsbDrDaqGetValues	19
12	UsbDrDaqGetValuesF	20
13	UsbDrDaqOpenUnit	21
14	UsbDrDaqOpenUnitAsync	22
15	UsbDrDaqOpenUnitProgress	23
16	UsbDrDaqPingUnit	24
17	UsbDrDaqReady	25
18	UsbDrDaqRun	26
19	UsbDrDaqSetDO	27
20	UsbDrDaqSetInterval	28
21	UsbDrDaqSetIntervalF	30
22	UsbDrDaqSetPWM	31
23	UsbDrDaqSetRGBLED	32
24	UsbDrDaqSetScalings	33
25	UsbDrDaqSetSigGenArbitrary	34
26	UsbDrDaqSetSigGenBuiltIn	35
27	UsbDrDaqSetTrigger	36
28	UsbDrDaqStartPulseCount	37
29	UsbDrDaqStop	38
30	UsbDrDaqStopSigGen	39

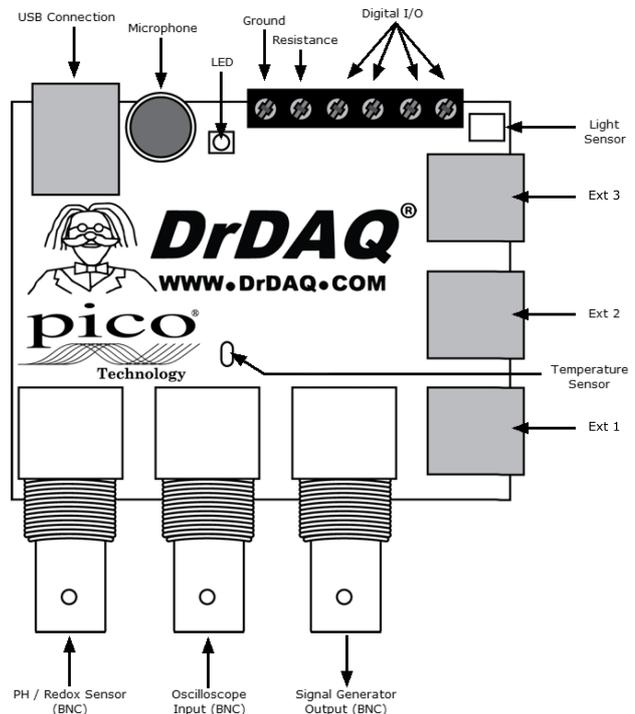
31 Channel numbers	39
32 PICO_STATUS values	40
4 Example code	42
5 Glossary	43
Index	45

1 Introduction

1.1 Overview

The USB DrDAQ PC Data Logger is a medium-speed, multichannel voltage-input device for sampling data using a PC. This manual explains how to use the Application Programming Interface and drivers to write your own programs to control the unit. You should read it in conjunction with the *USB DrDAQ User's Guide*.

The Software Development Kit for the USB DrDAQ is compatible with 32-bit and 64-bit editions of Microsoft Windows XP (SP3), Windows Vista, Windows 7, Windows 8 and Windows 10.



1.2 License agreement

Grant of license. The material contained in this release is licensed, not sold. Pico Technology Limited ("Pico") grants a license to the person who installs this software, subject to the conditions listed below.

Access. The licensee agrees to allow access to this software only to persons who have been informed of and agree to abide by these conditions.

Usage. The software in this release is for use only with Pico products or with data collected using Pico products.

Copyright. The software in this release is for use only with Pico products or with data collected using Pico products. You may copy and distribute the SDK without restriction, as long as you do not remove any Pico Technology copyright statements. The example programs in the SDK may be modified, copied and distributed for the purpose of developing programs to collect data using Pico products.

Liability. Pico and its agents shall not be liable for any loss or damage, howsoever caused, related to the use of Pico equipment or software, unless excluded by statute.

Fitness for purpose. No two applications are the same, so Pico cannot guarantee that its equipment or software is suitable for a given application. It is therefore the user's responsibility to ensure that the product is suitable for the user's application.

Mission-critical applications. Because the software runs on a computer that may be running other software products, and may be subject to interference from these other products, this license specifically excludes usage in "mission-critical" applications, for example life-support systems.

Viruses. This software was continuously monitored for viruses during production. However, the user is responsible for virus checking the software once it is installed.

Support. No software is ever error-free, but if you are dissatisfied with the performance of this software, please contact our technical support staff.

Upgrades. We provide upgrades, free of charge, from our web site at www.picotech.com. We reserve the right to charge for updates or replacements sent out on physical media.

1.3 Trademarks

Pico Technology, PicoScope, PicoLog and **DrDAQ** are trademarks of Pico Technology Limited, registered in the United Kingdom and other countries.

PicoLog and **Pico Technology** are registered in the U.S. Patent and Trademark Office.

Windows and **Excel** are registered trademarks of Microsoft Corporation in the USA and other countries.

1.4 Software updates

Our software is regularly updated with new features. To check what version of the software you are running, start PicoScope or PicoLog and select the **Help > About** menu. PicoScope can check for updates automatically and advise you if an update is available. You can download the latest versions of the software free of charge from the Pico Technology web site at:

<https://www.picotech.com/downloads>

Alternatively, the latest software can be purchased on disk from Pico Technology.

To be kept up-to-date with news of new software releases, click [here](#) to join our e-mail mailing list.

2 Writing your own software

2.1 About the driver

USB DrDAQ is supplied with a kernel driver and a DLL, `UsbDrDaq.dll`, containing routines that you can build into your own programs. The driver is supported by the following operating systems:

- Microsoft Windows XP (SP3 or later)
- Microsoft Windows Vista
- Microsoft Windows 7
- Microsoft Windows 8
- Microsoft Windows 10

and is supplied in 32-bit and 64-bit versions.

The SDK contains the drivers, a selection of examples of how to use them, and the current *Programmer's Guide*.

The driver supports up to 64 units at one time.

2.2 Installing the driver

The drivers are supplied with the USB DrDAQ SDK. You can download the latest 32-bit and 64-bit versions of the SDK from our website at:

<https://www.picotech.com/downloads>

Click **PicoLog Data Loggers > DrDAQ > Software > PicoSDK**

2.3 Connecting the logger

Before you connect your logger, you must first [install the driver](#).

To connect the data logger, plug the cable provided into any available USB port on your PC. The first time you connect the unit, some versions of Windows may display a New Hardware Wizard. Follow any instructions in the Wizard and wait for the driver to be installed. The unit is then ready for use.

2.4 Capture modes

Three modes are available for capturing data:

- `BM_SINGLE`: collect a single block of data and exit
- `BM_WINDOW`: collect a series of overlapping blocks of data
- `BM_STREAM`: collect a continuous stream of data

`BM_SINGLE` is useful when you wish to collect data at high speed for a short period: for example, to collect 1000 readings in 50 milliseconds. The maximum block size is 16,384 samples, shared between all active channels.

`BM_WINDOW` is useful when collecting several blocks of data at low speeds - for example when collecting 10,000 samples over 10 seconds. Collecting a sequence of single blocks like this would take 10 seconds for each block, so displayed data would not be updated frequently. Using windowing, it is possible to ask for a new block more frequently, for example every second, and to receive a block containing 9 seconds of repeat data and 1 second of new data. The block is effectively a 10-second window that advances one second per cycle.

`BM_STREAM` is useful when you need to collect data continuously for long periods. In principle, it could be used to collect data indefinitely. Every time [UsbDrDagGetValues](#) is called, it returns the new readings since the last time it was called. The `noOfValues` argument passed to [UsbDrDagRun](#) must be sufficient to ensure that the buffer does not overflow between successive calls to [UsbDrDagGetValues](#). For example, if you call [UsbDrDagGetValues](#) every second and you are collecting 500 samples per second, `noOfValues` must be at least 500, or preferably 1000, to allow for delays in the operating system.

2.5 USB DrDAQ scaling files (.DDS)

The DrDAQ driver has built-in scaling for each of the built-in and Pico-supplied sensors. You can incorporate scaling for your own sensors by adding a file called [scaling.dds](#) (where "scaling" can be replaced with a name of your choice). This file will contain the details of your sensor.

The values returned by the driver are integers that represent fixed-point decimal numbers. For example, the driver treats pH as a value with two decimal places, so a pH of 7.65 is returned as 765.

You can call the routine [UsbDrDagGetChannelInfo](#) to find out how many decimal places a channel is using, and also to get a divider that converts the integer value to the corresponding real number. For pH, the returned divider is 100, so 765 divided by 100 gives 7.65.

For some sensors, there is more than one possible scaling available. You can call [UsbDrDagGetScalings](#) to get a list of valid scaling codes, then call [UsbDrDagSetScalings](#) to select one of them. Once selected, [UsbDrDagGetChannelInfo](#) will return full information about the selected scaling. If you do not use [UsbDrDagSetScalings](#), the driver will automatically select the first available scaling for each channel.

USB DrDAQ scaling files can be used to supplement the scalings built into the driver. Several DDS files may be used, and these must be placed in the current working directory where the USB DrDAQ software is installed. The total number of sets of scaling data in all the files used must not exceed 99.

Each scaling file may contain more than one set of scaling data. Each scaling must have a unique scaling number, contained in the `[Scale...]` section heading.

A set of typical entries from a `.DDS` file is shown below:

```
[Scale1]
Resistor=1
LongName=CustomTemperature1
ShortName=TempC
Units=C
MinValue=-40
MaxValue=120
OutOfRange=0
```

```

Places=1
Method=0
IsFast=Yes
NoOfPoints=32
Raw1=2.385
Scaled1=-30
...
Raw32=1.32
Scaled32=100

[Scale2]
Resistor=2.2
LongName=CustomTemperature2
ShortName=TempF
Units=F
MinValue=32
MaxValue=160
...
[Scale3]
Resistor=3.3
LongName=CustomLight
ShortName=Light
Units=lux
MinValue=0
MaxValue=20000
...

```

The meanings of the terms in the .DDS file are as follows:

```
[Scale1]
```

A unique number, from 1 to 99, to identify this entry. (Pico-created numbers are from 100 upwards.)

```
Resistor=1
```

The ID resistor value in kilohms. In this example "1" represents 1k, "2.2" represents 2k2 and so on.

For external sensors, this resistor should be fitted in the sensor. You must use one of the following resistors: 1k0, 2k2, 3k3, 5k6, 7k5 or 10k. The resistor must be 1% tolerance or better.

For internal sensors, use the following "virtual" resistor values:

Channel	Resistor value
Sound Waveform	1200
Sound Level	1300
Voltage	1500
Resistance	1600
pH	1400
Temperature	1100
Light	1000

```
LongName=Temperature
```

Used in PicoLog

```
ShortName=TempC
```

This field is not used by USB DrDAQ running PicoScope or PicoLog.

```
Units=C
```

Displayed on graphs

```
MinValue=-40
```

```
MaxValue=120
```

Note: For PicoScope these values will determine the maximum and minimum values displayed in Scope View. For PicoLog these values determine what Maximum range is displayed in the Graph View (set in the **Graph Options** dialog).

```
Places=1
```

Number of decimal places. The options are 0, 1, 2 and 3. With `places=1` the value 15.743 would be returned as 15.7, meaning 15.7. With `places=2`, the same value would be returned as 15.74.

```
Method=0
```

This specifies the scaling method. 0 specifies table lookup and 1 specifies linear scaling.

```
Offset=0
```

```
Gain=1
```

These are the offset and gain values for linear scaling.

```
OutOfRange=0
```

This specifies what to do if the raw value is outside the range of the table lookup. The options are:

0 - treat as a sensor failure

1 - clip the value to the minimum or maximum table value

2 - extrapolate the value using the nearest two table entries.

```
ScopeRange=1.25V
```

This is used when scaling the oscilloscope channel. It specifies the range of the oscilloscope channel that should be used. Possible values are 10 V, 5 V, 2.5 V, and 1.25 V.

```
NoOfPoints=32
```

This is the number of table lookup points.

```
Raw1=2.385
```

Raw value for the first point in the look up table. The value is in V (volts) and should not be greater than 2.500 V.

```
Scaled1=-30
```

Scaled value for the first point in the look up table. The units are specified by the units parameter.

3 USB DrDAQ API functions

The following table explains each of the driver functions supplied with the USB DrDAQ data logger:

Routine	Description
UsbDrDaqCloseUnit	close the unit
UsbDrDaqEnableRGBLED	enable or disable RGB mode on the LED
UsbDrDaqGetChannelInfo	return a set of information about the currently selected scaling for the specified channel
UsbDrDaqGetInput	configure the general-purpose I/Os as digital inputs
UsbDrDaqGetPulseCount	return the current pulse count
UsbDrDaqGetScalings	discover the scalings, both built-in and custom, that are available
UsbDrDaqGetSingle	get a single value from a specified channel
UsbDrDaqGetSingleF	get a single floating-point value
UsbDrDaqGetTriggerTimeOffsetNs	return the time between the trigger point and the first post-trigger sample
UsbDrDaqGetUnitInfo	return various items of information about the unit
UsbDrDaqGetValues	get a number of sample values after a run
UsbDrDaqGetValuesF	get floating-point values after a run
UsbDrDaqOpenUnit	open and enumerate the unit
UsbDrDaqOpenUnitAsync	open the unit without waiting for completion
UsbDrDaqOpenUnitProgress	report progress of UsbDrDaqOpenUnitAsync
UsbDrDaqPingUnit	check that a device is connected
UsbDrDaqReady	indicate when UsbDrDaqRun has captured data
UsbDrDaqRun	tell the unit to start capturing data
UsbDrDaqSetDO	control the digital outputs
UsbDrDaqSetInterval	set the sampling speed of the unit (integer)
UsbDrDaqSetIntervalF	set the sampling speed of the unit (floating-point)
UsbDrDaqSetPWM	configure the general-purpose I/Os as pulse-width modulation outputs
UsbDrDaqSetRGBLED	set the color of the LED once RGB mode has been enabled
UsbDrDaqSetScalings	set the scaling for a particular channel
UsbDrDaqSetSigGenArbitrary	allow full control of the arbitrary waveform generator
UsbDrDaqSetSigGenBuiltIn	set the arbitrary waveform generator using standard waveform types
UsbDrDaqSetTrigger	set the trigger on the unit
UsbDrDaqStartPulseCount	configure the general-purpose I/Os for pulse counting and start counting
UsbDrDaqStop	abort data collection
UsbDrDaqStopSigGen	turn the AWG off

The driver allows you to do the following:

- Identify and open the logger
- Take a single reading from a particular channel
- Collect a block of samples at fixed time intervals from one or more channels
- Set up a trigger event for a particular channel
- Get information about scalings available for a channel
- Select a scaling for a channel
- Control and read general-purpose I/Os
- Control arbitrary waveform generator

You can specify a sampling interval from 1 microsecond to 1 second. The shortest interval that the driver will accept depends on the [capture mode](#) selected.

The normal calling sequence to collect a block of data is as follows:

```
Check that the driver version is correct
Open the driver
Set trigger mode (if required)
Set sampling mode (channels and time per sample)

While you want to take measurements,
  Run
  While not ready
    Wait
  End while
  ... Get a block of data ...
End While
Close the driver
```

3.1 UsbDrDaqCloseUnit

```
PICO\_STATUS UsbDrDaqCloseUnit  
(  
    int16_t          handle  
)
```

This function closes the unit.

Arguments:	handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress
Returns:	PICO_OK PICO_HANDLE_INVALID

3.2 UsbDrDaqEnableRGBLED

```

PICO_STATUS UsbDrDaqEnableRGBLED
(
    int16_t          handle,
    int16_t          enabled
)

```

This function enables or disables RGB mode on the LED.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>enabled: if non-zero, RGB mode is enabled. If zero RGB mode is disabled and the LED returns to normal operation (flashing when sampling).</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING</p>

3.3 UsbDrDaqGetChannelInfo

```

PICO STATUS UsbDrDaqGetChannelInfo
(
    int16_t          handle,
    float            * min,
    float            * max,
    int16_t          * places,
    int16_t          * divider,
    USB_DRDAQ_INPUTS channel
)

```

This procedure returns a set of information about the currently selected scaling for the specified channel. If a parameter is not required, you can pass a null pointer to the routine.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>min: on exit, the minimum value that the channel can take</p> <p>max: on exit, the maximum value that the channel can take</p> <p>places: on exit, the number of decimal places</p> <p>divider: on exit, the number that values should be divided by to give real numbers</p> <p>channel: the channel to return details for. See Channel numbers.</p>
Returns:	<p>PICO_OK</p> <p>PICO_NOT_FOUND</p> <p>PICO_INVALID_PARAMETER</p>

3.4 UsbDrDaqGetInput

```

PICO STATUS UsbDrDaqGetInput
(
    int16_t          handle,
    USB_DRDAQ_GPIO IOChannel,
    int16_t          pullUp,
    int16_t          * value
)

```

This function is used to configure the general-purpose I/Os as digital inputs.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>IOChannel: all GPIOs can be used as digital inputs. See Channel numbers</p> <p>pullUp: used to specify whether pull-up resistor is used</p> <p>value: on exit, indicates the state of the input (0 or 1)</p>
Returns:	<p>PICO_OK</p> <p>PICO_NOT_FOUND</p> <p>PICO_NOT_RESPONDING</p> <p>PICO_INVALID_PARAMETER</p>

3.5 UsbDrDagGetPulseCount

```
PICO STATUS UsbDrDagGetPulseCount
(
    int16_t          handle,
    USB_DRDAQ_GPIO  IOChannel,
    int16_t          * count
)
```

This function will return the current pulse count. It should be called after pulse counting has been started using [UsbDrDagStartPulseCount](#).

Arguments:	<p><code>handle</code>: device identifier returned from UsbDrDagOpenUnit or UsbDrDagOpenUnitProgress</p> <p><code>IOChannel</code>: which GPIO to use. See Channel numbers</p> <p><code>count</code>: on exit, contains the current count</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING PICO_INVALID_PARAMETER</p>

3.6 UsbDrDaqGetScalings

```

PICO_STATUS UsbDrDaqGetScalings
(
    int16_t          handle
    USB_DRDAQ_INPUTS channel,
    int16_t          * nScales,
    int16_t          * currentScale,
    int8_t           * names,
    int16_t          namesSize
)

```

This function discovers the scalings, both built-in and custom, that are available for a particular channel.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>channel: the channel number</p> <p>nScales: output. The function writes the number of available scales here.</p> <p>currentScale: output. An index to the currently selected scale here.</p> <p>names: output. A string containing the scaling names and indices.</p> <p>namesSize: the size of names</p>
Returns:	<p>PICO_OK</p> <p>PICO_NOT_FOUND</p> <p>PICO_INVALID_CHANNEL</p>

3.7 UsbDrDagGetSingle

```
PICO STATUS UsbDrDagGetSingle
(
    int16_t          handle,
    USB_DRDAQ_INPUTS channel,
    int16_t          * value,
    uint16_t         * overflow
)
```

This function returns a single sample value from the specified input channel.

See [UsbDrDagGetSingleF](#) for a similar function that returns a floating-point sample value.

Arguments:	<p>handle: device identifier returned from UsbDrDagOpenUnit or UsbDrDagOpenUnitProgress</p> <p>channel: which channel to sample. See Channel numbers.</p> <p>value: on exit, the sample value</p> <p>overflow: on exit, a bit field indicating which, if any, input channels overflowed the input range of the device. A bit set to 1 indicates an overflow. The least significant bit corresponds to channel 1. May be NULL if an overflow warning is not required.</p>
Returns:	<pre><code>PICO_OK PICO_INVALID_HANDLE PICO_NO_SAMPLES_AVAILABLE PICO_DEVICE_SAMPLING PICO_NULL_PARAMETER PICO_INVALID_PARAMETER PICO_DATA_NOT_AVAILABLE PICO_INVALID_CALL PICO_NOT_RESPONDING PICO_MEMORY</code></pre>

3.8 UsbDrDaqGetSingleF

```
PICO STATUS UsbDrDaqGetSingleF  
(  
    int16_t          handle,  
    USB_DRDAQ_INPUTS channel,  
    float            * value,  
    uint16_t         * overflow  
)
```

This function returns a single floating-point sample value from the specified input channel. In all other respects it is the same as [UsbDrDaqGetSingle](#).

3.9 UsbDrDaqGetTriggerTimeOffsetNs

```
PICO_STATUS UsbDrDaqGetTriggerTimeOffsetNs  
(  
    int16_t          handle,  
    int64_t          * time  
)
```

This function returns the time between the trigger point and the first post-trigger sample. This is calculated using linear interpolation.

Arguments:	handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress time: on exit, trigger time in nanoseconds
Returns:	PICO_OK PICO_NOT_FOUND

3.10 UsbDrDagGetUnitInfo

```

PICO_STATUS UsbDrDagGetUnitInfo
(
    int16_t          handle,
    int8_t           * string,
    int16_t          stringLength,
    int16_t          * requiredSize,
    PICO_INFO        info
)

```

This function returns a string containing the specified item of information about the unit.

If you want to find out the length of the string before allocating a buffer for it, call the function with `string = NULL` first.

Arguments:	<p><code>handle</code>: device identifier returned from UsbDrDagOpenUnit or UsbDrDagOpenUnitProgress</p> <p><code>string</code>: location of a buffer where the function writes the requested information, or <code>NULL</code> if you are only interested in the value of <code>requiredSize</code></p> <p><code>stringLength</code>: the maximum number of characters that the function should write to <code>string</code></p> <p><code>requiredSize</code>: on exit, the length of the information string before it was truncated to <code>stringLength</code>. If the string was not truncated, <code>requiredSize</code> will be less than or equal to <code>stringLength</code>.</p> <p><code>info</code>: the information that the driver should return. These values are specified in <code>picoStatus.h</code>.</p> <pre> PICO_DRIVER_VERSION PICO_USB_VERSION PICO_HARDWARE_VERSION PICO_VARIANT_INFO PICO_BATCH_AND_SERIAL PICO_CAL_DATE PICO_KERNEL_DRIVER_VERSION </pre>
Returns:	<pre> PICO_OK PICO_INVALID_HANDLE PICO_NULL_PARAMETER PICO_INVALID_INFO PICO_INFO_UNAVAILABLE </pre>

3.11 UsbDrDagGetValues

```

PICO STATUS UsbDrDagGetValues
(
    int16_t          handle,
    int16_t          * values,
    uint32_t         * noOfValues,
    uint16_t         * overflow,
    uint32_t         * triggerIndex
)

```

This function is used to get values after calling [UsbDrDagRun](#).

See [UsbDrDagGetValuesF](#) for a similar function that gets floating-point values.

Arguments:	<p>handle: device identifier returned from UsbDrDagOpenUnit or UsbDrDagOpenUnitProgress</p> <p>values: an array of sample values returned by the function. The size of this buffer must be the number of enabled channels multiplied by the number of samples to be collected.</p> <p>Note: The order of the channels will be as stated in Channel numbers, regardless of the order used in the UsbDrDagSetInterval channels array.</p> <p>noOfValues: on entry, the number of sample values per channel that the function should collect. On exit, the number of samples per channel that were actually written to the buffer.</p> <p>overflow: on exit, a bit field indicating which, if any, input channels overflowed the input range of the device. A bit set to 1 indicates an overflow. The least significant bit corresponds to channel 1. May be NULL if an overflow warning is not required.</p> <p>triggerIndex: on exit, a number indicating when the trigger event occurred. The number is a zero-based index to the <code>values</code> array, or 0xFFFFFFFF if the information is not available. On entry, the pointer may be NULL if a trigger index is not required.</p>
Returns:	<p>PICO_OK PICO_INVALID_HANDLE PICO_NO_SAMPLES_AVAILABLE PICO_DEVICE_SAMPLING PICO_NULL_PARAMETER PICO_INVALID_PARAMETER PICO_TOO_MANY_SAMPLES PICO_DATA_NOT_AVAILABLE PICO_INVALID_CALL PICO NOT RESPONDING PICO MEMORY</p>

3.12 UsbDrDaqGetValuesF

```
PICO STATUS UsbDrDaqGetValuesF
(
    int16_t          handle,
    float            * values,
    uint32_t         * noOfValues,
    uint16_t         * overflow,
    uint32_t         * triggerIndex
)
```

This function is used to get floating-point values after calling [UsbDrDaqRun](#). In all other respects it is the same as [UsbDrDaqGetValues](#).

3.13 UsbDrDaqOpenUnit

```
PICO\_STATUS UsbDrDaqOpenUnit  
(  
    int16_t          * handle  
)
```

This function opens and enumerates the unit.

Arguments:	<code>handle</code> : on exit, a value that uniquely identifies the data logger that was opened. Use this as the <code>handle</code> parameter when calling any other UsbDrDaq API function.
Returns:	PICO_OK PICO_OS_NOT_SUPPORTED PICO_OPEN_OPERATION_IN_PROGRESS PICO_EEPROM_CORRUPT PICO_KERNEL_DRIVER_TOO_OLD PICO_FW_FAIL PICO_MAX_UNITS_OPENED PICO_NOT_FOUND PICO_NOT_RESPONDING

3.14 UsbDrDaqOpenUnitAsync

```
PICO\_STATUS UsbDrDaqOpenUnitAsync
(
    int16_t          * status
)
```

This function opens a USB DrDAQ data logger without waiting for the operation to finish. You can find out when it has finished by periodically calling [UsbDrDaqOpenUnitProgress](#) until that function returns a non-zero value and a valid data logger handle.

The driver can support up to 64 data loggers.

Arguments:	status: on exit, a status flag: 0 if there is already an open operation in progress 1 if the open operation is initiated
Returns:	PICO_OK PICO_OPEN_OPERATION_IN_PROGRESS PICO_OPERATION_FAILED

3.15 UsbDrDagOpenUnitProgress

```
PICO\_STATUS UsbDrDagOpenUnitProgress
(
    int16_t          * handle,
    int16_t          * progress,
    int16_t          * complete
)
```

This function checks on the progress of [UsbDrDagOpenUnitAsync](#).

Arguments:	<p>* <code>handle</code>: on exit, the device identifier of the opened data logger, if the operation was successful. Use this as the <code>handle</code> parameter when calling any other USB DrDAQ API function.</p> <p>0: if no unit is found or the unit fails to open</p> <p><>0: handle of unit (valid only if function returns <code>PICO_OK</code>)</p> <p><code>progress</code>: on exit, an estimate of the progress towards opening the data logger. The value is between 0 to 100.</p> <p><code>complete</code>: on exit, a non-zero value if the operation has completed, otherwise zero</p>
Returns:	<p><code>PICO_OK</code> <code>PICO_NULL_PARAMETER</code> <code>PICO_OPERATION_FAILED</code></p>

3.16 UsbDrDaqPingUnit

```
PICO\_STATUS UsbDrDaqPingUnit  
(  
    int16_t          * handle  
)
```

This function checks that the specified USB DrDAQ is connected.

Arguments:	handle: the device identifier returned by UsbDrDaqOpenUnit or related function
Returns:	PICO_OK PICO_NOT_RESPONDING PICO_BUSY PICO_DRIVER_FUNCTION PICO_NOT_FOUND

3.17 UsbDrDaqReady

```
PICO\_STATUS UsbDrDaqReady  
(  
    int16_t          handle,  
    int16_t          * ready  
)
```

This function indicates when [UsbDrDaqRun](#) has captured the requested number of samples.

Arguments:	<code>handle</code> : device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress <code>ready</code> : TRUE if ready, FALSE otherwise
Returns:	PICO_OK PICO_INVALID_HANDLE PICO_NOT_RESPONDING

3.18 UsbDrDaqRun

```

PICO STATUS UsbDrDaqRun
(
    int16_t          handle,
    uint32_t         no_of_values,
    BLOCK_METHOD    method
)

```

This function tells the unit to start capturing data.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>no_of_values: the number of samples the unit should collect</p> <p>method: which method to use to collect the data, from the following list:</p> <ul style="list-style-type: none"> BM_SINGLE BM_WINDOW BM_STREAM <p>See Capture modes for details.</p>
Returns:	<p>PICO_OK</p> <p>PICO_INVALID_HANDLE</p> <p>PICO_USER_CALLBACK</p> <p>PICO_INVALID_CHANNEL</p> <p>PICO_TOO_MANY_SAMPLES</p> <p>PICO_INVALID_TIMEBASE</p> <p>PICO_NOT_RESPONDING</p> <p>PICO_CONFIG_FAIL</p> <p>PICO_INVALID_PARAMETER</p> <p>PICO_NOT_RESPONDING</p> <p>PICO_TRIGGER_ERROR</p>

3.19 UsbDrDaqSetDO

```
PICO STATUS UsbDrDaqSetDO
(
    int16_t          handle,
    USB_DRDAQ_GPIO IOChannel,
    int16_t          value
)
```

This function is used to configure the general-purpose I/Os as digital outputs.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>IOChannel: identifies the channel. See Channel numbers.</p> <p>value: any non-zero value sets the digital output and zero clears it</p>
Returns:	<p>PICO_OK</p> <p>PICO_NOT_FOUND</p> <p>PICO_NOT_RESPONDING</p> <p>PICO_INVALID_PARAMETER</p>

3.20 UsbDrDaqSetInterval

```
PICO STATUS UsbDrDaqSetInterval
(
    int16_t          handle,
    uint32_t        * us_for_block,
    uint32_t        ideal_no_of_samples,
    USB_DRDAQ_INPUTS * channels,
    int16_t         no_of_channels
)
```

This function sets the [sampling interval](#) of the unit. Sampling of multiple channels is sequential.

The minimum possible sampling interval (si_{min} , in microseconds) depends on the [capture mode](#) and number of active channels (n) as follows:

- [BM SINGLE](#) mode:

$$si_{min} = n$$

- [BM WINDOW](#) and [BM STREAM](#) modes:

$$si_{min} = 10 * n$$

If you wish to know the effective sampling interval (si , in microseconds) set by this function, you can calculate it as follows:

$$si = (ideal_no_of_samples * no_of_channels) / us_for_block$$

Arguments:	<p><code>handle</code>: on exit, device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p><code>us_for_block</code>: on entry, the target total time in which to collect <code>ideal_no_of_samples</code>, in microseconds. On exit, the actual total time that was set. For more accurate setting of total time as a floating-point value, use UsbDrDaqSetIntervalF.</p> <p><code>ideal_no_of_samples</code>: the number of samples per channel that you want to collect. This number is used only for timing calculations. In BM SINGLE mode, the total for all active channels must not exceed 16,384 samples.</p> <p><code>channels</code>: an array of constants identifying the channels from which you wish to capture data. See the list at Channel numbers. If you specify the channels in a different order from that shown in that list, the function will re-order them.</p> <p><code>no_of_channels</code>: the number of channels in the <code>channels</code> array.</p>
-------------------	----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------

Returns:	PICO_OK PICO_INVALID_HANDLE PICO_INVALID_CHANNEL PICO_INVALID_TIMEBASE PICO_NOT_RESPONDING PICO_CONFIG_FAIL PICO_INVALID_PARAMETER PICO_NOT_RESPONDING PICO_TRIGGER_ERROR
-----------------	---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------

3.21 `UsbDrDaqSetIntervalF`

```
PICO STATUS UsbDrDaqSetIntervalF  
(  
    int16_t          handle,  
    float           * us_for_block,  
    uint32_t        ideal_no_of_samples,  
    USB_DRDAQ_INPUTS * channels,  
    int16_t         no_of_channels  
)
```

This function sets the sampling interval of the unit. It works in the same way as [UsbDrDaqSetInterval](#) except that the `us_for_block` argument is a `float` instead of an integer.

3.22 UsbDrDaqSetPWM

```
PICO\_STATUS UsbDrDaqSetPWM
(
    int16_t          handle,
    USB_DRDAQ_GPIO  IOChannel,
    uint16_t         period,
    uint8_t          cycle
)
```

This function is used to configure the general-purpose I/Os as pulse-width modulation outputs.

Arguments:	<p><code>handle</code>: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p><code>IOChannel</code>: GPIOs 1 and 2 can be used as PWM outputs. See UsbDrDaqSetDO for values.</p> <p><code>period</code>: the period of the waveform in microseconds</p> <p><code>cycle</code>: duty cycle as a percentage</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING PICO_INVALID_PARAMETER</p>

3.23 UsbDrDaqSetRGBLED

```
PICO STATUS UsbDrDaqSetRGBLED
(
    int16_t          handle,
    uint16_t         red,
    uint16_t         green,
    uint16_t         blue
)
```

This function is used to set the color of the LED once RGB mode has been enabled using [USBDRDaqEnableRGBLED](#).

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress.</p> <p>red, green, blue: components of the required LED color, in the range 0 to 255.</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING</p>

3.24 UsbDrDaqSetScalings

```
PICO STATUS UsbDrDaqSetScalings  
(  
    int16_t          handle  
    USB_DRDAQ_INPUTS channel,  
    int16_t          scalingNumber  
)
```

This function sets the scaling for a specified channel.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>channel: the channel to set. See Channel numbers.</p> <p>scalingNumber: the number of the required scale, as given by UsbDrDaqGetScalings</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_INVALID_CHANNEL PICO_INVALID_PARAMETER</p>

3.25 UsbDrDaqSetSigGenArbitrary

```

PICO STATUS UsbDrDaqSetSigGenArbitrary
(
    int16_t          handle,
    int32_t          offsetVoltage,
    uint32_t         pkToPk,
    int16_t          * arbitraryWaveform,
    int16_t          arbitraryWaveformSize,
    int32_t          updateRate
)

```

This function allows full control of the arbitrary waveform generator by allowing an arbitrary waveform to be passed to the driver.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>offsetVoltage: the offset voltage in microvolts. The offset voltage must be in the range -1.5 V to 1.5 V.</p> <p>pkToPk: the peak-to-peak voltage in microvolts. The maximum allowed is 3 V.</p> <p>arbitraryWaveform: an array containing the waveform. The waveform values must be in the range -1000 to 1000.</p> <p>arbitraryWaveformSize: the number of points in the waveform.</p> <p>updateRate: the rate at which the AWG steps through the points in the waveform. This value must be in the range 1 to 2,000,000 points per second.</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING PICO_INVALID_PARAMETER</p>

3.26 UsbDrDagSetSigGenBuiltIn

```
PICO STATUS UsbDrDagSetSigGenBuiltIn
(
    int16_t          handle,
    int32_t          offsetVoltage,
    uint32_t         pkToPk,
    int16_t          frequency,
    USB_DRDAQ_WAVE  waveType
)
```

This function sets the arbitrary waveform generator using standard waveform types.

Arguments:	<p>handle: device identifier returned from UsbDrDagOpenUnit or UsbDrDagOpenUnitProgress</p> <p>offsetVoltage: the offset voltage in microvolts. The offset voltage must be in the range -1.5 V to 1.5 V.</p> <p>pkToPk: the peak-to-peak voltage in microvolts. The maximum allowed is 3 V.</p> <p>frequency: frequency in hertz. The maximum allowed frequency is 20 kHz.</p> <p>waveType: an enumerated data type that has the following values corresponding to standard waveforms:</p> <ul style="list-style-type: none"> USB_DRDAQ_SINE USB_DRDAQ_SQUARE USB_DRDAQ_TRIANGLE USB_DRDAQ_RAMP_UP USB_DRDAQ_RAMP_DOWN USB_DRDAQ_DC
Returns:	<ul style="list-style-type: none"> PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING PICO_INVALID_PARAMETER

3.27 UsbDrDaqSetTrigger

```

PICO STATUS UsbDrDaqSetTrigger
(
    int16_t          handle,
    uint16_t         enabled,
    uint16_t         auto_trigger,
    uint16_t         auto_ms,
    uint16_t         channel,
    uint16_t         dir,
    int16_t          threshold,
    uint16_t         hysteresis,
    float            delay
)

```

This function sets up the trigger, which controls when the unit starts capturing data.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>enabled: whether to enable or disable the trigger: 0: disable the trigger 1: enable the trigger</p> <p>auto_trigger: whether or not to re-arm the trigger automatically after each trigger event: 0: do not auto-trigger 1: auto-trigger</p> <p>auto_ms: time in milliseconds after which the unit will auto-trigger if the trigger condition is not met</p> <p>channel: which channel to trigger on. See Channel numbers.</p> <p>dir: which edge to trigger on: 0: rising edge 1: falling edge</p> <p>threshold: trigger threshold (the level at which the trigger will activate) in the currently selected scaling, multiplied to remove any decimal places. The number of decimal places can be found by calling UsbDrDAQGetChannelInfo.</p> <p>hysteresis: trigger hysteresis in ADC counts. This is the difference between the upper and lower thresholds. The signal must then pass through both thresholds in the same direction in order to activate the trigger, so that there are fewer unwanted trigger events caused by noise. The minimum value allowed is 1.</p> <p>delay: delay between the trigger event and the start of the block as a percentage of the block size. 0% means that the trigger event is the first data value in the block, and -50% means that the trigger event is in the middle of the block.</p>
Returns:	PICO_OK PICO_INVALID_HANDLE PICO_USER_CALLBACK PICO_TRIGGER_ERROR PICO_MEMORY_FAIL

3.28 UsbDrDaqStartPulseCount

```
PICO STATUS UsbDrDaqStartPulseCount
(
    int16_t          handle,
    USB_DRDAQ_GPIO IOChannel,
    int16_t          direction
)
```

This function is used to configure the general-purpose I/Os for pulse counting and to start counting.

Arguments:	<p>handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress</p> <p>IOChannel: specifies the GPIO channel to use, either GPIO 1 or GPIO 2. See Channel numbers.</p> <p>direction: the direction of the edges to count (0: rising, 1: falling).</p>
Returns:	<p>PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING PICO_INVALID_PARAMETER</p>

3.29 UsbDrDaqStop

```
PICO\_STATUS UsbDrDaqStop  
(  
    int16_t          handle  
)
```

This function aborts data collection.

Arguments:	handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress
Returns:	PICO_OK PICO_INVALID_HANDLE

3.30 UsbDrDaqStopSigGen

```
PICO\_STATUS UsbDrDaqStopSigGen
(
    int16_t          handle
)
```

This function turns the AWG off.

Arguments:	handle: device identifier returned from UsbDrDaqOpenUnit or UsbDrDaqOpenUnitProgress
Returns:	PICO_OK PICO_NOT_FOUND PICO_NOT_RESPONDING

3.31 Channel numbers

Use the following values for the `channel` argument in those API functions that deal with a specified input channel or channels:

```
typedef enum enUsbDrDaqInputs
{
    USB_DRDAQ_CHANNEL_EXT1 = 1,    //Ext. sensor 1           // 1
    USB_DRDAQ_CHANNEL_EXT2,      //Ext. sensor 2           // 2
    USB_DRDAQ_CHANNEL_EXT3,      //Ext. sensor 3           // 3
    USB_DRDAQ_CHANNEL_SCOPE,     //Scope channel           // 4
    USB_DRDAQ_CHANNEL_PH,        //PH                       // 5
    USB_DRDAQ_CHANNEL_RES,       //Resistance               // 6
    USB_DRDAQ_CHANNEL_LIGHT,     //Light                   // 7
    USB_DRDAQ_CHANNEL_TEMP,      //Thermistor              // 8
    USB_DRDAQ_CHANNEL_MIC_WAVE,  //Microphone waveform     // 9
    USB_DRDAQ_CHANNEL_MIC_LEVEL, //Microphone level        // 10
    USB_DRDAQ_MAX_CHANNELS = USB_DRDAQ_CHANNEL_MIC_LEVEL
} USB_DRDAQ_INPUTS;
```

Use the following values for the `IOChannel` argument in the API functions that deal with a specified GPIO channel:

```
typedef enum enUsbDrDaqDO
{
    USB_DRDAQ_GPIO_1 = 1,        // 1
    USB_DRDAQ_GPIO_2,           // 2
    USB_DRDAQ_GPIO_3,           // 3
    USB_DRDAQ_GPIO_4            // 4
} USB_DRDAQ_GPIO;
```

Source: `usbDrDaqApi.h` 2013-01-22

3.32 PICO_STATUS values

Every function in the USB DrDAQ API returns a status code from the following list of PICO_STATUS values:

Code (hex)	Enum	Description
00	PICO_OK	The Data Logger is functioning correctly
01	PICO_MAX_UNITS_OPENED	An attempt has been made to open more than <code>UsbDrDaq_MAX_UNITS</code>
02	PICO_MEMORY_FAIL	Not enough memory could be allocated on the host machine
03	PICO_NOT_FOUND	No USB DrDAQ device could be found
04	PICO_FW_FAIL	Unable to download firmware
05	PICO_OPEN_OPERATION_IN_PROGRESS	A request to open a device is in progress
06	PICO_OPERATION_FAILED	The operation was unsuccessful
07	PICO_NOT_RESPONDING	The device is not responding to commands from the PC
08	PICO_CONFIG_FAIL	The configuration information in the device has become corrupt or is missing
09	PICO_KERNEL_DRIVER_TOO_OLD	The <code>picopp.sys</code> file is too old to be used with the device driver
0A	PICO_EEPROM_CORRUPT	The EEPROM has become corrupt, so the device will use a default setting
0B	PICO_OS_NOT_SUPPORTED	The operating system on the PC is not supported by this driver
0C	PICO_INVALID_HANDLE	There is no device with the handle value passed
0D	PICO_INVALID_PARAMETER	A parameter value is not valid
0E	PICO_INVALID_TIMEBASE	The sampling interval is not supported or is invalid
0F	PICO_INVALID_VOLTAGE_RANGE	The voltage range is not supported or is invalid
10	PICO_INVALID_CHANNEL	The channel number is not valid on this device or no channels have been set
11	PICO_INVALID_TRIGGER_CHANNEL	The channel set for a trigger is not available on this device
12	PICO_INVALID_CONDITION_CHANNEL	The channel set for a condition is not available on this device
13	PICO_NO_SIGNAL_GENERATOR	The device does not have a signal generator
14	PICO_STREAMING_FAILED	Streaming has failed to start or has stopped without user request
15	PICO_BLOCK_MODE_FAILED	Block failed to start - a parameter may have been set wrongly
16	PICO_NULL_PARAMETER	A parameter that was required is <code>NULL</code>
18	PICO_DATA_NOT_AVAILABLE	No data is available from a run block call
19	PICO_STRING_BUFFER_TOO_SMALL	The buffer passed for the information was too small
1A	PICO_ETS_NOT_SUPPORTED	ETS is not supported on this device
1B	PICO_AUTO_TRIGGER_TIME_TOO_SHORT	The auto trigger time is less than the time it will take to collect the data
1C	PICO_BUFFER_STALL	The collection of data has stalled as unread data would be overwritten
1D	PICO_TOO_MANY_SAMPLES	The number of samples requested is more than available in the current memory segment
1E	PICO_TOO_MANY_SEGMENTS	Not possible to create number of segments requested

1F	PICO_PULSE_WIDTH_QUALIFIER	A null pointer has been passed in the trigger function or one of the parameters is out of range
20	PICO_DELAY	One or more of the hold-off parameters are out of range
21	PICO_SOURCE_DETAILS	One or more of the source details are incorrect
22	PICO_CONDITIONS	One or more of the conditions are incorrect
23	PICO_USER_CALLBACK	The driver's thread is currently in the UsbDrDagReady callback function and therefore the action cannot be carried out
24	PICO_DEVICE_SAMPLING	An attempt is being made to get stored data while streaming. Either stop streaming by calling UsbDrDagStop .
25	PICO_NO_SAMPLES_AVAILABLE	...because a run has not been completed
26	PICO_SEGMENT_OUT_OF_RANGE	The memory index is out of range
27	PICO_BUSY	Data cannot be returned yet
28	PICO_STARTINDEX_INVALID	The start time to get stored data is out of range
29	PICO_INVALID_INFO	The information number requested is not a valid number
2A	PICO_INFO_UNAVAILABLE	The handle is invalid so no information is available about the device. Only PICO_DRIVER_VERSION is available.
2B	PICO_INVALID_SAMPLE_INTERVAL	The sample interval selected for streaming is out of range
2C	PICO_TRIGGER_ERROR	Not used
2D	PICO_MEMORY	Driver cannot allocate memory
36	PICO_DELAY_NULL	NULL pointer passed as delay parameter
37	PICO_INVALID_BUFFER	The buffers for overview data have not been set while streaming
3A	PICO_CANCELLED	A block collection has been canceled
3B	PICO_SEGMENT_NOT_USED	The segment index is not currently being used
3C	PICO_INVALID_CALL	The wrong GetValues function has been called for the collection mode in use
3F	PICO_NOT_USED	The function is not available
41	PICO_INVALID_STATE	Device is in an invalid state
43	PICO_DRIVER_FUNCTION	You called a driver function while another driver function was still being processed

4 Example code

Your PicoScope SDK installation includes programming examples in various languages and development environments. Please refer to the SDK for details.

5 Glossary

Driver. A program that controls a piece of hardware. The driver for the USB DrDAQ is supplied in the form of 32-bit and 64-bit versions of a Windows DLL, `UsbDrDaq.dll`. This is used by the PicoScope and PicoLog software, and by user-designed applications, to control the data logger.

PicoLog software. A program supplied with all PicoLog devices that turns your PC into a data logger with charting, spreadsheet and monitoring features.

PicoScope software. A software product that accompanies all PicoScope oscilloscopes. It turns your PC into an oscilloscope, spectrum analyzer and multimeter.

Sampling interval. The time interval between samples as the USB DrDAQ acquires data. The sampling interval can be set to any value returned by the [UsbDrDaqSetInterval](#) and [UsbDrDaqSetIntervalF](#) functions.

USB 2.0. Universal Serial Bus. This is a standard port that enables you to connect external devices to PCs. A full-speed USB 2.0 port operates at up to 480 megabits per second. The PicoLog 1000 Series is also compatible with any USB port from USB 1.1 upwards.

Voltage range. The range of input voltages that the oscilloscope can measure. For example, a voltage range of ± 100 mV means that the oscilloscope can measure voltages between -100 mV and $+100$ mV. Input voltages outside this range will not damage the instrument as long as they remain within the protection limits stated in the Specifications table in the User's Guide.



Index

A

- Arbitrary waveform generator 34, 35
- Asynchronous operation 3

B

- BM_SINGLE mode 3
- BM_STREAM mode 3
- BM_WINDOW mode 3

C

- Capture modes
 - BM_SINGLE 3
 - BM_STREAM 3
 - BM_WINDOW 3
- Channel information, obtaining 11
- Channel numbers 39
- Closing a unit 9
- Connecting to the PC 3

D

- Data, reading 15, 16, 19, 20
- Device information, obtaining 18
- Device status, querying 25
- Digital inputs 12
- Digital outputs 27
- DLLs 3
- Driver routines
 - list of 7
 - UsbDrDaqCloseUnit 9
 - UsbDrDaqEnableRGBLED 10
 - UsbDrDaqGetChannelInfo 11
 - UsbDrDaqGetInput 12
 - UsbDrDaqGetPulseCount 13
 - UsbDrDaqGetScalings 14
 - UsbDrDaqGetSingle 15
 - UsbDrDaqGetSingleF 16
 - UsbDrDaqGetTriggerTimeOffsetNs 17
 - UsbDrDaqGetUnitInfo 18
 - UsbDrDaqGetValues 19
 - UsbDrDaqGetValuesF 20
 - UsbDrDaqOpenUnit 21
 - UsbDrDaqOpenUnitAsync 22
 - UsbDrDaqOpenUnitProgress 23
 - UsbDrDaqPingUnit 24
 - UsbDrDaqReady 25

- UsbDrDaqRun 26
- UsbDrDaqSetDO 27
- UsbDrDaqSetInterval 28
- UsbDrDaqSetIntervalF 30
- UsbDrDaqSetPWM 31
- UsbDrDaqSetRGBLED 32
- UsbDrDaqSetScalings 33
- UsbDrDaqSetSigGenArbitrary 34
- UsbDrDaqSetSigGenBuiltIn 35
- UsbDrDaqSetTrigger 36
- UsbDrDaqStartPulseCount 37
- UsbDrDaqStop 38
- UsbDrDaqStopSigGen 39

I

- Information on device, obtaining 18
- Installation 3

L

- LED 10, 32
- Legal information 1

N

- New Hardware Wizard 3

O

- Opening a device 21, 22, 23

P

- PICO_STATUS 40
- Programming 3
- Pulse counter 13, 37
- PWM outputs, setting up 31

Q

- Querying a device 24

R

- Running a device 26

S

- Sampling interval, setting 28, 30
- Scaling
 - files 4
 - querying 14
 - setting 33

Signal generator
 configuring 35
 stopping 39
Software updates 2
Stopping a unit 38
Streaming 3

T

Trademarks 2
Trigger
 configuring 36
 reading times 17

U

USB DrDAQ 1

W

Windows
 64-bit 3
 WoW64 3
 XP/Vista/7/8 support 3

UK headquarters

Pico Technology
James House
Colmworth Business Park
St. Neots
Cambridgeshire
PE19 8YP
United Kingdom

Tel: +44 (0) 1480 396 395
Fax: +44 (0) 1480 396 296

sales@picotech.com
support@picotech.com

www.picotech.com

USA headquarters

Pico Technology
320 N Glenwood Blvd
Tyler
Texas 75702
United States

Tel: +1 800 591 2796
Fax: +1 620 272 0981