



PT-104

USB/Ethernet RTD Data Logger

Programmer's Guide



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1 Introduction

1.1 Overview

The PT-104 is a four-channel, high-resolution data logger for use with PT100 and PT1000 type platinum resistance thermometer (PRT) sensors. As well as temperature, it can also be used to measure resistance and voltage.

Additional information

For instructions on connecting and using the device, and setting it up with the PicoLog software, please see the *PT-104 Data Logger User's Guide* available on www.picotech.com.



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2 Driver information

The Pico Technology software development kit (SDK) is available in 32-bit and 64-bit versions and contains the drivers and a selection of examples showing how to use them. It also contains a copy of this manual as a PDF file.

The driver function is supplied as a Windows DLL, [usbpt104.dll](#), which can be used with a number of programs. It is available in 32-bit and 64-bit versions.

3 API functions

These are the API functions provided by the driver:

- [UsbPt104CloseUnit](#) Close the port (do this each time you finish using the device!)
- [UsbPt104Enumerate](#) Get list of attached devices.
- [UsbPt104GetUnitInfo](#) Retrieve information about this PT-104.
- [UsbPt104GetValue](#) Get the most recent data reading from a channel.
- [UsbPt104IpDetails](#) Read or write IP settings.
- [UsbPt104OpenUnit](#) Open the device through its USB interface.
- [UsbPt104OpenUnitViaIp](#) Open the device through its Ethernet interface.
- [UsbPt104SetChannel](#) Specify the sensor type and filtering for a channel.
- [UsbPt104SetMains](#) Change the mains noise filtering setting to 60 Hz. The default is 50 Hz.

The normal calling sequence for these functions is as follows:

```
Open Driver
Set Channels
While you want to read data
    Get data
End While
Close Unit
Close Driver
```


3.1 UsbPt104CloseUnit

```
PICO_STATUS UsbPt104CloseUnit (  
    int16_t  handle  
)
```

This function disconnects the driver.

Arguments:	<code>handle</code> , identifies the device to close
Returns:	defined in <code>picoStatus.h</code>

3.2 UsbPt104Enumerate

```
PICO_STATUS UsbPt104Enumerate (
    int8_t          * details,
    uint32_t        * length,
    COMMUNICATION_TYPE type
)
```

This function returns a list of all the attached PT-104 devices of the specified port type.

Arguments:	<p><code>details</code>, a string buffer to receive a maximum of <code>length</code> characters. The string is a comma-separated list of attached devices of the selected <code>type</code>. The buffer must be long enough to accommodate the expected string.</p> <p>USB devices are listed in this format:</p> <pre>USB:Serial Number</pre> <p>Example: <code>USB:CT264/118</code></p> <p>Ethernet devices are listed in this format:</p> <pre>IP:Serial Number[IP Address:port]</pre> <p>Example: <code>IP:CT264/118[192.168.1.253:6500]</code></p> <p><code>length</code>, input: the length of the <code>details</code> buffer output: the length of the information string returned</p> <p><code>type</code>, the communication type used by the PT-104. Can be any of the following enumerated types:</p> <pre>CT_USB = 0x00000001 (lists only USB-connected devices) CT_ETHERNET = 0x00000002 (lists only Ethernet-connected devices) CT_ALL = 0xFFFFFFFF (lists all devices regardless of connection type)</pre>
Returns:	defined in <code>picoStatus.h</code>

3.3 UsbPt104GetUnitInfo

```
PICO_STATUS UsbPt104GetUnitInfo (
    int16_t    handle,
    int8_t     * string,
    int16_t    stringLength,
    int16_t    * requiredSize,
    PICO_INFO  info
)
```

This function obtains information on a specified device.

Arguments:	<p><code>handle</code>, identifies the device whose information is required</p> <p><code>string</code>, output: the information requested</p> <p><code>stringLength</code>, input: the length of the <code>string</code> buffer</p> <p><code>requiredSize</code>, output: the length of the information string requested. If this is longer than <code>stringLength</code> then only the first <code>stringLength</code> characters of the requested information are written to <code>string</code>.</p> <p><code>info</code>, the type of information required. The following types are defined in <code>picoStatus.h</code>:</p> <pre>PICO_DRIVER_VERSION PICO_USB_VERSION PICO_HARDWARE_VERSION PICO_VARIANT_INFO PICO_BATCH_AND_SERIAL PICO_CAL_DATE PICO_KERNEL_DRIVER_VERSION</pre>
Returns:	defined in <code>picoStatus.h</code>

3.4 UsbPt104GetValue

```
PICO_STATUS UsbPt104GetValue (
    int16_t      handle,
    USBPT104_CHANNELS channel,
    int32_t      * value,
    int16_t      filtered
)
```

Once you open the driver and define some channels, the driver begins to take continuous readings from the PT-104. When you call this function, it immediately sets data to the most recent reading for the specified channel.

The scaling of measurements is as follows:

Range	Scaling
Temperature	<code>value</code> × 1/1000 °C
Voltage (0 to 2.5 V)	<code>value</code> × 10 nV
Voltage (0 to 115 mV)	<code>value</code> × 1 nV
Resistance (0 to 375 Ω)	<code>value</code> × 1 μΩ
Resistance (0 to 10 kΩ)	<code>value</code> × 1 mΩ

Arguments:	<p><code>handle</code>, identifies the device from which to get data</p> <p><code>channel</code>, the number of the channel to read, from 1 to 4 in differential mode or 1 to 8 in single-ended mode</p> <p><code>value</code>, output: the requested reading</p> <p><code>filtered</code>, if set to <code>TRUE</code>, the driver returns a low-pass filtered value of the temperature. The time constant of the filter depends on the channel parameters as set by UsbPt104SetChannel, and on how many channels are active.</p>
Returns:	defined in picoStatus.h

3.5 UsbPt104IpDetails

```
PICO_STATUS UsbPt104IpDetails (
    int16_t      handle,
    int16_t      * enabled,
    int8_t       * ipaddress,
    uint16_t     * length,
    uint16_t     * listeningPort,
    IP_DETAILS_TYPE type
)
```

This function either reads or writes the IP details of a specified device. The `type` argument controls whether the operation is a read or a write.

Arguments:	<p><code>handle</code>, identifies the device that is the target of the operation</p> <p><code>enabled</code>, input: 1 to enable the device, 0 to disable output: 1 if the device is enabled, 0 if disabled</p> <p><code>ipaddress</code>, input or output: the IP address of the device</p> <p style="padding-left: 40px;">Example: <code>192.168.1.253</code></p> <p><code>length</code>, input or output: the length of the IP address string</p> <p><code>listeningPort</code>, input or output: the local IP port connected to the device</p> <p><code>type</code>, the type of operation to be performed. Can be either of the following types:</p> <p style="padding-left: 40px;"><code>IDT_GET</code>, to read information from the driver</p> <p style="padding-left: 40px;"><code>IDT_SET</code>, to write information to the driver</p>
Returns:	defined in <code>picoStatus.h</code>

3.6 UsbPt104OpenUnit

```
PICO_STATUS UsbPt104OpenUnit (  
    int16_t * handle,  
    int8_t * serial  
)
```

This function obtains a handle for the PT-104 device with the given serial number.

If you wish to use more than one PT-104, you must call the function once for each device.

Arguments:	<code>handle</code> , output: handle of the device that was opened. This value is used to identify the device in all further function calls. <code>serial</code> , input: serial number string of device, null-terminated
Returns:	defined in <code>picoStatus.h</code>

3.7 UsbPt104OpenUnitViaIp

```
PICO_STATUS UsbPt104OpenUnitViaIp (
    int16_t * handle,
    int8_t * serial,
    int8_t * ipAddress
)
```

This function obtains a handle for the Ethernet-connected PT-104 device, identified by either its IP address or its serial number.

- Using IP address identification, a device anywhere on the internet or local network can be opened.
- Using serial number identification, only a device on the local network can be opened.

If you wish to use more than one PT-104, you must call the function once for each device.

To control the device directly through the Ethernet port without using the usbpt104 DLL, see [Ethernet protocol](#).

Arguments:	<p><code>handle</code>, output: handle of the device that was opened. This value is used to identify the device in all further function calls.</p> <p><code>serial</code>, input: serial number of device as a null-terminated string, or a null pointer if <code>ipAddress</code> is used</p> <p><code>ipAddress</code>, input: the IP address of the device as a null-terminated string, or a null pointer if <code>serial</code> is used</p> <p>Example: for IP address 192.168.1.253 and listening port 6500, use the string: <code>192.168.1.253:6500</code></p>
Returns:	defined in <code>picoStatus.h</code>

3.8 UsbPt104SetChannel

```
PICO_STATUS UsbPt104SetChannel (
    int16_t          handle,
    USBPT104_CHANNELS channel,
    USBPT104_DATA_TYPES type,
    int16_t          noOfWires
)
```

This function configures a single channel of the specified PT-104. It can be called any time after calling [UsbPt104OpenUnit](#).

The fewer channels selected, the more frequently they will be updated. Measurement takes about 720 ms per active channel.

If a call to [UsbPt104SetChannel](#) has a `type` of single-ended, then the specified channel's 'sister' channel is also enabled. For example, enabling 3 also enables 7.

Arguments:	<p><code>handle</code>, identifies the device to be configured</p> <p><code>channel</code>, which channel you want to set the details for. It should be between 1 and 4 if using single-ended inputs in voltage mode.</p> <p><code>type</code>, the type of reading you require. Choose from the table below.</p> <p><code>noOfWires</code>, how many wires the PT100 or PT1000 sensor has (2, 3 or 4)</p>
Returns:	defined in <code>picoStatus.h</code>

USBPT104_DATA_TYPES		Data type
<code>USBPT104_OFF</code>	0	disable channel
<code>USBPT104_PT100</code>	1	PT100
<code>USBPT104_PT1000</code>	2	PT1000
<code>USBPT104_RESISTANCE_TO_375R</code>	3	resistance 0 to 350
<code>USBPT104_RESISTANCE_TO_10K</code>	4	resistance 0 to 10 k
<code>USBPT104_DIFFERENTIAL_TO_115MV</code>	5	differential voltage 0 to 100 mV
<code>USBPT104_DIFFERENTIAL_TO_2500MV</code>	6	differential voltage 0 to 2.5 V
<code>USBPT104_SINGLE_ENDED_TO_115MV</code>	7	single-ended voltage 0 to 100 mV
<code>USBPT104_SINGLE_ENDED_TO_2500MV</code>	8	single-ended voltage 0 to 2.5 V

3.9 UsbPt104SetMains

```
PICO_STATUS UsbPt104SetMains (  
    int16_t    handle,  
    uint16_t   sixty_hertz  
)
```

This function is used to inform the driver of the local mains (line) frequency. This helps the driver to filter out electrical noise.

Arguments:	<code>handle</code> , identifies the device to be configured <code>sixty_hertz</code> , for 50 Hz set to 0; for 60 Hz set to 1
Returns:	defined in <code>picoStatus.h</code>

4 Constants and enumerated types

```
#define USBPT104_MIN_WIRES 2
#define USBPT104_MAX_WIRES 4

typedef enum enUsbPt104Channels
{
    USBPT104_CHANNEL_1 = 1,
    USBPT104_CHANNEL_2,
    USBPT104_CHANNEL_3,
    USBPT104_CHANNEL_4,
    USBPT104_CHANNEL_5,
    USBPT104_CHANNEL_6,
    USBPT104_CHANNEL_7,
    USBPT104_CHANNEL_8,
    USBPT104_MAX_CHANNELS = USBPT104_CHANNEL_8
} USBPT104_CHANNELS;

typedef enum enUsbPt104DataType
{
    USBPT104_OFF,
    USBPT104_PT100,
    USBPT104_PT1000,
    USBPT104_RESISTANCE_TO_375R,
    USBPT104_RESISTANCE_TO_10K,
    USBPT104_DIFFERENTIAL_TO_115MV,
    USBPT104_DIFFERENTIAL_TO_2500MV,
    USBPT104_SINGLE_ENDED_TO_115MV,
    USBPT104_SINGLE_ENDED_TO_2500MV,
    USBPT104_MAX_DATA_TYPES
} USBPT104_DATA_TYPES;

typedef enum enIpDetailsType
{
    IDT_GET,
    IDT_SET,
} IP_DETAILS_TYPE;

typedef enum enCommunicationType
{
    CT_USB = 0x00000001,
    CT_ETHERNET = 0x00000002,
    CT_ALL = 0xFFFFFFFF
} COMMUNICATION_TYPE;
```

5 Programming examples

Your Pico Technology SDK installation includes programming examples in various languages and development environments. Please refer to the SDK for details.

6 Ethernet protocol

Using the protocol described below, the PT-104 can be controlled directly through the Ethernet port without using the USBPT104 DLL.

6.1 Enabling the Ethernet module

By default the Ethernet module is disabled to save power. To enable it, plug the connector into a USB port and use the Ethernet settings application installed with PicoLog. Once an IP address and port are assigned, the module will be enabled. The unit may then be used by powering from USB or PoE.

6.2 Finding Ethernet PT-104s

To discover all PT-104 data loggers on a network:

- Send a UDP packet to port 23 from port 23 (telnet) to destination 255.255.255.255 with this character string:

```
fff
```

(three bytes of 0x66 - that is, 0x666666)

- All PT-104s will reply from port 23 to port 23. The data will be the string:

```
PT104 Mac:XXXXXX Lock:Y Port:ZZ
```

where:

XXXXXX is the 6-byte MAC address of the PT-104 replying

Y is 0x00 for unlocked and 0x01 for locked

ZZ is the port it will listen on (two bytes, MSB first).

6.2.1 Commands

- To lock a PT-104 to a machine, a UDP packet destined for the device's listening port and IP address should be sent containing the data string `lock`. This is required before the PT-104 is usable.

UDP packet data in the form Command + Data bytes:

Command	Data bytes	Function
0x30	0x00 for 50 Hz Any other byte for 60 Hz	Change mains frequency rejection
0x31	One byte, bit 0 is LSB Bit 0: enable channel 1 Bit 1: enable channel 2 Bit 2: enable channel 3 Bit 3: enable channel 4 Bit 4: channel 1 gain Bit 5: channel 2 gain Bit 6: channel 3 gain Bit 7: channel 4 gain	Start converting enable: 0 - off 1 - on gain: 0 - x1 1 - x21 (for 375 range)
0x32	-	Read EPROM
0x33	-	Unlock
0x34	-	Keep alive

Unlock / timeout stops the transfer of any channel data. Unlock should be used when the application no longer requires the unit so that it is unlocked for use with other machines.

6.3 Unlocked unit response

The response from an unlocked unit is described in [Finding Ethernet PT-104s](#).

6.4 Locked unit responses

- Lock Success
- Lock Success (already locked to this machine)
- Unlocked
- The string EEPROM= followed by a byte[128] array (see table below)
- Converting
- Mains Changed
- Unknown Command
- Alive
- [hex] 00 XX XX XX XX 01 XX XX XX XX 02 XX XX XX XX 03 XX XX XX XX data from channel 1
where XX is a byte of the 4-byte measurement value, most-significant byte first.
The 4-byte values are measurements 0, 1, 2 and 3.
- [hex] 04 XX XX XX XX 05 XX XX XX XX 06 XX XX XX XX 07 XX XX XX XX data from channel 2
- [hex] 08 XX XX XX XX 09 XX XX XX XX 0a XX XX XX XX 0b XX XX XX XX data from channel 3
- [hex] 0c XX XX XX XX 0d XX XX XX XX 0e XX XX XX XX 0f XX XX XX XX data from channel 4

A unit that has been locked will reply `Lock Success` or, if currently locked by this machine, `Lock Success (already locked to this machine)`.

`Converting` is an acknowledgment of any convert request received. Once a setting has been made the unit will continue to convert and send back data. This means there will be incoming data approximately every 720 ms. To stop all converting, send a converting command with data `0x00` to turn off all channels.

After receiving the `lock` command via UDP, a 15 s timeout will start and a keep-alive packet must be sent in this time. The `Alive` response is the acknowledgment. Try to send a keep-alive packet every 10 seconds to allow time to retry if no acknowledgment is received.

If any request is made from another machine while a unit is locked then the response will be `PT104 Mac:XXXXXX Lock:Y Port:ZZ` as explained in [Finding Ethernet PT-104s](#).

EEPROM FORMAT

Index	NumBytes	Data
0	19	Reserved
19	10	Batch
29	8	Calibration Date
37	4	Ch1 Calibration (LSB first)
41	4	Ch2 Calibration (LSB first)
45	4	Ch3 Calibration (LSB first)
49	4	Ch4 Calibration (LSB first)
53	6	MAC Address
59	67	Reserved
126	2	Checksum

6.5 To calculate a resistance

- Read the EEPROM to obtain the calibration information for the channels.
- Take measurement 0, 1, 2 and 3 on a channel.
- Note that measurements are stored MSB-first while calibration values are stored LSB-first.
- Then:
$$\text{result} = \frac{\text{channel calibration} * (\text{measurement 3} - \text{measurement 2})}{(\text{measurement 1} - \text{measurement 0})}$$
- To convert to a resistance, divide *result* by 1 000 000.0.

For other measurement types see the Protocol information in the serial port *PT-104 User's Guide*.

7 Technical reference

7.1 Lookup table

Here is the resistance–temperature characteristic for a PT100 sensor:

Temp (°C)	Resistance (Ω)
-50	80.306282
-49	80.703340
-48	81.100257
-47	81.497036
-46	81.893677
-45	82.290179
-44	82.686545
-43	83.082774
-42	83.478868
-41	83.874827
-40	84.270652
-39	84.666343
-38	85.061901
-37	85.457327
-36	85.852622
-35	86.247785
-34	86.642818
-33	87.037721
-32	87.432495
-31	87.827140
-30	88.221657
-29	88.616046
-28	89.010309
-27	89.404445
-26	89.798455
-25	90.192339
-24	90.586099
-23	90.979734
-22	91.373246
-21	91.766634
-20	92.159898
-19	92.553041
-18	92.946061
-17	93.338960
-16	93.731737
-15	94.124394
-14	94.516930
-13	94.909346
-12	95.301643
-11	95.693820
-10	96.085879
-9	96.477819
-8	96.869641
-7	97.261345
-6	97.652931
-5	98.044401
-4	98.435753
-3	98.826989
-2	99.218109
-1	99.609112
0	100.000000

1	100.390772
2	100.781429
3	101.171970
4	101.562396
5	101.952706
6	102.342901
7	102.732980
8	103.122944
9	103.512792
10	103.902525
11	104.292142
12	104.681644
13	105.071030
14	105.460301
15	105.849456
16	106.238496
17	106.627420
18	107.016229
19	107.404922
20	107.793500
21	108.181962
22	108.570309
23	108.958540
24	109.346656
25	109.734656
26	110.122541
27	110.510310
28	110.897964
29	111.285502
30	111.672925
31	112.060232
32	112.447424
33	112.834500
34	113.221461
35	113.608306
36	113.995036
37	114.381650
38	114.768149
39	115.154532
40	115.540800
41	115.926952
42	116.312989
43	116.698910
44	117.084716
45	117.470406
46	117.855981
47	118.241440
48	118.626784
49	119.012012
50	119.397125
51	119.782122
52	120.167004
53	120.551770
54	120.936421
55	121.320956
56	121.705376
57	122.089680
58	122.473869

59	122.857942
60	123.241900
61	123.625742
62	124.009469
63	124.393080
64	124.776576
65	125.159956
66	125.543221
67	125.926370
68	126.309404
69	126.692322
70	127.075125
71	127.457812
72	127.840384
73	128.222840
74	128.605181
75	128.987406
76	129.369516
77	129.751510
78	130.133389
79	130.515152
80	130.896800
81	131.278332
82	131.659749
83	132.041050
84	132.422236
85	132.803306
86	133.184261
87	133.565100
88	133.945824
89	134.326432
90	134.706925
91	135.087302
92	135.467564
93	135.847710
94	136.227741
95	136.607656
96	136.987456
97	137.367140
98	137.746709
99	138.126162
100	138.505500
101	138.884722
102	139.263829
103	139.642820
104	140.021696
105	140.400456
106	140.779101
107	141.157630
108	141.536044
109	141.914342
110	142.292525
111	142.670592
112	143.048544
113	143.426380
114	143.804101
115	144.181706
116	144.559196

117	144.936570
118	145.313829
119	145.690972
120	146.068000
121	146.444912
122	146.821709
123	147.198390
124	147.574956
125	147.951406
126	148.327741
127	148.703960
128	149.080064
129	149.456052
130	149.831925
131	150.207682
132	150.583324
133	150.958850
134	151.334261
135	151.709556
136	152.084736
137	152.459800
138	152.834749
139	153.209582
140	153.584300
141	153.958902
142	154.333389
143	154.707760
144	155.082016
145	155.456156
146	155.830181
147	156.204090
148	156.577884
149	156.951562
150	157.325125
151	157.698572
152	158.071904
153	158.445120
154	158.818221
155	159.191206
156	159.564076
157	159.936830
158	160.309469
159	160.681992
160	161.054400
161	161.426692
162	161.798869
163	162.170930
164	162.542876
165	162.914706
166	163.286421
167	163.658020
168	164.029504
169	164.400872
170	164.772125
171	165.143262
172	165.514284
173	165.885190
174	166.255981

175	166.626656
176	166.997216
177	167.367660
178	167.737989
179	168.108202
180	168.478300
181	168.848282
182	169.218149
183	169.587900
184	169.957536
185	170.327056
186	170.696461
187	171.065750
188	171.434924
189	171.803982
190	172.172925
191	172.541752
192	172.910464
193	173.279060
194	173.647541
195	174.015906
196	174.384156
197	174.752290
198	175.120309
199	175.488212
200	175.856000



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